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Difference-Type Estimators for Estimation of Mean in The Presence of Measurement Error

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Abstract

In this paper we have suggested difference-type estimator for estimation of population mean of the study variable y in the presence of measurement error using auxiliary information. The optimum estimator in the suggested estimator has been identified along with its mean square error formula. It has been shown that the suggested estimator performs more efficient then other existing estimators. An empirical study is also carried out to illustrate the merits of proposed method over other traditional methods.

Key Words: Study variable, Auxiliary variable, Measurement error, Simple random Sampling, Bias, Mean Square error.

1. PERFORMANCE OF SUGGESTED METHOD USING SIMPLE RANDOM SAMPLING

INTRODUCTION

The present study deals with the impact of measurement errors on estimating population mean of study variable (y) in simple random sampling using auxiliary information. In theory of survey sampling, the properties of estimators based on data are usually presupposed that the observations are the correct measurement on the characteristic being studied. When the measurement errors are negligible small, the statistical inference based on observed data continue to remain valid.

An important source of measurement error in survey data is the nature of variables (study and auxiliary). Here nature of variable signifies that the exact measurement on variables is not available. This may be due to the following three reasons:

- 1. The variable is clearly defined but it is hard to take correct observation at least with the currently available techniques or because of other types of practical difficulties. Eg: The level of blood sugar in a human being.
- 2. The variable is conceptually well defined but observation can obtain only on some closely related substitutes known as Surrogates. Eg: The measurement of economic status of a person.
- 3. The variable is fully comprehensible and well understood but it is not intrinsically defined. Eg: Intelligence, aggressiveness etc.

Some authors including Singh and Karpe (2008, 2009), Shalabh(1997), Allen et al. (2003), Manisha and Singh (2001, 2002), Srivastava and Shalabh (2001), Kumar et al. (2011 a,b), Malik and Singh (2013), Malik et al. (2013) have paid their attention towards the estimation of population mean μ_y of study variable using auxiliary information in the presence of measurement errors. Fuller (1995) examined the importance of measurement errors in estimating parameters in sample surveys. His major concerns are estimation of population mean or total and its standard error, quartile estimation and estimation through regression model.

SYMBOLS AND SETUP

Let, for a SRS scheme (x_i, y_i) be the observed values instead of true values (X_i, Y_i) on two characteristics (x, y), respectively for all i=(1,2,...n) and the observational or measurement errors are defined as

$$\mathbf{u}_{i} = (\mathbf{y}_{i} - \mathbf{Y}_{i}) \tag{1}$$

$$\mathbf{v}_{\mathbf{i}} = (\mathbf{x}_{\mathbf{i}} - \mathbf{X}_{\mathbf{i}}) \tag{2}$$

where u_i and v_i are stochastic in nature with mean 0 and variance σ_u^2 and σ_v^2 respectively. For the sake of convenience, we assume that u_i 's and v_i 's are uncorrelated although X_i 's and Y_i 's are correlated .Such a specification can be, however, relaxed at the cost of some algebraic complexity. Also assume that finite population correction can be ignored.

Further, let the population means and variances of (x, y) be (μ_x, μ_y) and (σ_x^2, σ_y^2) . σ_{xy} and ρ be the population covariance and the population correlation coefficient between x and y respectively. Also let $C_y = \frac{\sigma_y}{\mu_y}$ and $C_x = \frac{\sigma_x}{\mu_x}$ are the population coefficient of variation and C_{yx} is the population coefficients of covariance in y and x.

LARGE SAMPLE APPROXIMATION

Define:

$$e_0 = \frac{\overline{y} - \mu_y}{\mu_y}$$
 and $e_1 = \frac{\overline{x} - \mu_x}{\mu_x}$

where, \boldsymbol{e}_{0} and \boldsymbol{e}_{1} are very small numbers and $\left|\boldsymbol{e}_{i}\right|<1$ $(i=0,\!1)$.

Also,
$$E(e_i) = 0 (i = 0,1)$$

and,
$$E(e_0^2) = \theta C_y^2 \left(1 + \frac{\sigma_u^2}{\sigma_y^2} \right) = \delta_0$$
,

$$E(e_1^2) = \theta C_x^2 \left(1 + \frac{\sigma_v^2}{\sigma_x^2} \right) = \delta_1, E(e_0 e_1) = \theta \rho C_x C_y, \text{ where } \theta = \frac{1}{n}.$$

2. EXISTING ESTIMATORS AND THEIR PROPERTIES

Usual mean estimator is given by

$$\overline{y} = \sum_{i=1}^{n} \frac{y_i}{n} \tag{3}$$

Up to the first order of approximation the variance of \bar{y} is given by

$$Var(\overline{y}) = \theta \mu_y^2 \left(1 + \frac{\sigma_u^2}{\sigma_y^2} \right) C_y^2$$
 (4)

The usual ratio estimator is given by

$$\overline{y}_{R} = \overline{y} \left(\frac{\mu_{x}}{\overline{x}} \right) \tag{5}$$

where μ_x is known population mean of x.

The bias and MSE (\bar{y}_R), to the first order of approximation, are respectively, given

$$B(\overline{y}_R) = \theta \mu_y \left[\left(1 + \frac{\sigma_v^2}{\sigma_x^2} \right) C_x^2 - \rho C_y C_x \right]$$
 (6)

$$MSE(\overline{y}_R) = \theta \mu_y^2 \left[\left(1 + \frac{\sigma_u^2}{\sigma_y^2} \right) C_y^2 + \left(1 + \frac{\sigma_v^2}{\sigma_x^2} \right) C_x^2 - 2\rho C_y C_x \right]$$
(7)

The traditional difference estimator is given by

$$\overline{y}_{d} = \overline{y} + k(\mu_{x} - \overline{x}) \tag{8}$$

where, k is the constant whose value is to be determined.

Minimum mean square error of \overline{y}_d at optimum value of

$$k = \frac{\mu_y \rho C_y}{\mu_x \left(1 + \frac{\sigma_v^2}{\sigma_x^2} \right) C_x}, \text{ is given by}$$

$$MSE(\overline{y}_{d}) = \mu_{y}^{2} \theta \left(1 + \frac{\sigma_{u}^{2}}{\sigma_{y}^{2}}\right) C_{y}^{2} \left[1 - \frac{\rho^{2}}{\left(1 + \frac{\sigma_{u}^{2}}{\sigma_{y}^{2}}\right)\left(1 + \frac{\sigma_{v}^{2}}{\sigma_{x}^{2}}\right)}\right]$$
(9)

Srivastava (1967) suggested an estimator

$$\overline{y}_{S} = \overline{y} \left(\frac{\mu_{x}}{\overline{x}} \right)^{\ell_{1}}$$
 (10)

where, ℓ_1 is an arbitrary constant.

Up to the first of approximation, the bias and minimum mean square error of $\,\overline{y}_{\scriptscriptstyle S}\,$ at optimum

value of
$$\ell_1 = \frac{\rho C_y}{\left(1 + \frac{\sigma_v^2}{\sigma_x^2}\right) C_x}$$
 are respectively, given by

$$B(\overline{y}_s) = \mu_y \left[\frac{\ell_1(\ell_1 + 1)}{2} \theta \left(1 + \frac{\sigma_v^2}{\sigma_x^2} \right) C_x^2 - \ell_1 \theta \rho C_y C_x \right]$$
(11)

$$MSE(\overline{y}_{S}) = \mu_{y}^{2} \theta \left(1 + \frac{\sigma_{u}^{2}}{\sigma_{y}^{2}}\right) C_{y}^{2} \left[1 - \frac{\rho^{2}}{\left(1 + \frac{\sigma_{u}^{2}}{\sigma_{y}^{2}}\right)\left(1 + \frac{\sigma_{v}^{2}}{\sigma_{x}^{2}}\right)}\right]$$
(12)

Walsh (1970) suggested an estimator \bar{y}_w

$$\overline{y}_{w} = \overline{y} \left[\frac{\mu_{x}}{\ell_{2}\overline{x} + (1 - \ell_{2})\mu_{x}} \right]$$
(13)

where, ℓ_2 is an arbitrary constant.

Up to the first order of approximation, the bias and minimum mean square error of \bar{y}_w at

optimum value of
$$\ell_2 = \frac{\rho C_y}{\left(1 + \frac{\sigma_v^2}{\sigma_x^2}\right) C_x}$$
, are respectively, given by

$$B(\overline{y}_{w}) = \mu_{y}\theta \left| \ell_{2}^{2}C_{x}^{2} \left(1 + \frac{\sigma_{y}^{2}}{\sigma_{x}^{2}} \right) - \ell_{2}\rho C_{y}C_{x} \right|$$

$$(14)$$

$$MSE(\overline{y}_{w}) = \mu_{y}^{2} \theta \left(1 + \frac{\sigma_{u}^{2}}{\sigma_{y}^{2}}\right) C_{y}^{2} \left[1 - \frac{\rho^{2}}{\left(1 + \frac{\sigma_{u}^{2}}{\sigma_{y}^{2}}\right)\left(1 + \frac{\sigma_{v}^{2}}{\sigma_{x}^{2}}\right)}\right]$$
(15)

Ray and Sahai (1979) suggested the following estimator

$$\overline{y}_{RS} = (1 - \ell_3)\overline{y} + \ell_3\overline{y} \left(\frac{\overline{x}}{\mu_x}\right)$$
(16)

where, ℓ_3 is an arbitrary constant.

Up to the first order of approximation, the bias and mean square of \bar{y}_{RS} at optimum value of

$$\ell_3 = -\frac{\rho C_y}{\left(1 + \frac{\sigma_v^2}{\sigma_x^2}\right)}$$
 are respectively, given by

$$B(\overline{y}_{RS}) = \theta \ell_3 \mu_y \rho C_y C_x \tag{17}$$

$$MSE(\overline{y}_{RS}) = \mu_y^2 \theta \left(1 + \frac{\sigma_u^2}{\sigma_y^2} \right) C_y^2 \left[1 - \frac{\rho^2}{\left(1 + \frac{\sigma_u^2}{\sigma_y^2} \right) \left(1 + \frac{\sigma_v^2}{\sigma_x^2} \right)} \right]$$
(18)

3. SUGGESTED ESTIMATOR

Following Singh and Solanki (2013), we suggest the following difference-type class of estimators for estimating population mean \overline{Y} of study variable y as

$$t_{p} = \left[\alpha_{1}\overline{y} + \alpha_{2}\overline{x}^{*} + (1 - \alpha_{1} - \alpha_{2})\mu_{x}^{*}\right] \frac{\mu_{x}^{*}}{\overline{x}^{*}}$$

$$(19)$$

where (α_1,α_2) are suitably chosen scalars such that MSE of the proposed estimator is minimum, $\overline{x}^* (= \eta \overline{x} + \lambda)$, $\mu_x^* (= \eta \mu_x + \lambda)$ with (n,λ) are either constants or function of some known population parameters. Here it is interesting to note that some existing estimators have been shown as the members of proposed class of estimators t_p for different values of $(\alpha_1,\alpha_2,\alpha,\eta,\lambda)$, which is summarized in Table 1.

Table 1: Members of suggested class of estimators

Estimators		Values of Constants					
	$\alpha_{_1}$	α_2	α	η	λ		
y [Usual unbiased]	1	0	0	-	-		
\overline{y}_R [Usual ratio]	1	0	1	1	0		
\overline{y}_d [Usual difference]	1	α_2	0	-1	μ_{x}		
\overline{y}_{s} [Srivastava (1967)]	1	0	α	1	0		
\overline{y}_{DS} [Dubey and Singh]	$\alpha_{\scriptscriptstyle 1}$	$\alpha_{\scriptscriptstyle 2}$	0	1	0		

The properties of suggested estimator are derived in the following theorems.

Theorem 1.1: Estimator t_p in terms of e_i ; i = 0,1 expressed as:

$$\begin{split} t_{_{p}} = & \left[\mu_{_{x}}^{*} - \alpha A e_{_{1}} \mu_{_{x}}^{*} + B \mu_{_{x}}^{*} e_{_{1}}^{2} + \alpha_{_{1}} \left\{ \! C \! - \! \alpha A C e_{_{1}} + B C e_{_{1}}^{2} + e_{_{0}} \mu_{_{y}} - \! \alpha A \mu_{_{y}} e_{_{0}} e_{_{1}} \right\} \\ & + \alpha_{_{2}} \eta \mu_{_{x}} \left\{ \! e_{_{1}} \! - \! \alpha A e_{_{1}}^{2} \right\} \! \right] \end{split}$$

ignoring the terms $E(e_i^r e_j^s)$ for (r+s)>2, where r,s=0,1,2... and i=0,1; j=1 (first order of approximation).

where,
$$A = \frac{\eta \mu_x}{\eta \mu_x + \lambda}$$
, $B = \frac{\alpha(\alpha + 1)}{2} A^2$ and $C = \mu_y - \mu_x^*$.

Proof

$$\boldsymbol{t}_{p} = \left[\boldsymbol{\alpha}_{1}\overline{\boldsymbol{y}} + \boldsymbol{\alpha}_{2}\overline{\boldsymbol{x}}^{*} + (1 - \boldsymbol{\alpha}_{1} - \boldsymbol{\alpha}_{2})\boldsymbol{\mu}_{x}^{*}\right] \left[\frac{\boldsymbol{\mu}_{x}^{*}}{\overline{\boldsymbol{x}}^{*}}\right]^{\alpha}$$

Or

$$\mathbf{t}_{p} = \left[\alpha_{1} (1 + \mathbf{e}_{0}) + \alpha_{2} \eta \, \mu_{x} \mathbf{e}_{1} + (1 - \alpha_{1}) \mu_{x}^{*} \right] [1 + A \mathbf{e}_{1}]^{-\alpha}$$
(20)

We assume $|Ae_1| < 1$, so that the term $(1 + Ae_1)^{-\alpha}$ is expandable. Expanding the right hand side (20) and neglecting the terms of e's having power greater than two, we have

$$\begin{split} t_{p} &= \mu_{x}^{*} - \alpha A e_{1} \mu_{x}^{*} + B \mu_{x}^{*} e_{1}^{2} + \alpha_{1} \left\{ \! C \! - \! \alpha A C e_{1} + B C e_{1}^{2} + e_{0} \mu_{y} - \! \alpha A \mu_{y} e_{0} e_{1} \right\} \\ &+ \alpha_{2} \eta \mu_{x} \left\{ \! e_{1} \! - \! \alpha A e_{1}^{2} \right\} \end{split}$$

Theorem: 1.2 Bias of the estimator t_p is given by

$$B(t_{p}) = \left[B\mu_{x}^{*}\delta_{1} + \alpha_{1}\left\{BC\delta_{1} - \alpha A\mu_{y}\delta_{01}\right\} - \alpha_{2}\eta\mu_{x}A\alpha\delta_{1}\right]$$
(21)

Proof:

$$\begin{split} B(t_{_{p}}) &= E(t_{_{p}} - \mu_{_{y}}) \\ &= E\left[\mu_{_{x}}^{*} - \mu_{_{y}} - \alpha A e_{_{1}} \mu_{_{x}}^{*} + B \mu_{_{x}}^{*} e_{_{1}}^{2} + \alpha_{_{1}} \left\{ C - \alpha A C e_{_{1}} + B C e_{_{1}}^{2} + e_{_{0}} \mu_{_{y}} - \alpha A \mu_{_{y}} e_{_{0}} e_{_{1}} \right\} \\ &+ \alpha_{_{2}} \eta \mu_{_{x}} \left\{ e_{_{1}} - \alpha A e_{_{1}}^{2} \right\} \right] \\ &= \left[B \mu_{_{x}}^{*} \delta_{_{1}} + \alpha_{_{1}} \left\{ B C \delta_{_{1}} - \alpha A \mu_{_{y}} \delta_{_{01}} \right\} - \alpha_{_{2}} \eta \mu_{_{x}} A \alpha \delta_{_{1}} \right] \end{split}$$

where, δ_0 , δ_1 and δ_{01} are already defined in section 3.

Theorem 1.3: MSE of the estimator t_p , up to the first order of approximation is

$$\begin{split} MSE(t_{p}) &= \alpha_{1}^{2} \left\{ C^{2} + \mu_{y}^{2} \delta_{0} + \delta_{1} \left(\alpha^{2} A^{2} C^{2} + 2BC^{2} \right) - 4\alpha A C \mu_{y} \delta_{01} \right\} + \alpha_{2}^{2} \eta^{2} \mu_{x}^{2} \delta_{1} \\ &+ \left\{ C^{2} + \delta_{1} \left(\alpha^{2} A^{2} \mu_{x}^{2} - 2BC \mu_{x}^{*} \right) \right\} - 2\alpha_{1} \left\{ C^{2} + \delta_{1} \left(BC^{2} - BC \mu_{x}^{*} - \alpha^{2} A^{2} C \mu_{x}^{*} \right) + \delta_{01} \alpha A \mu_{y} \left(\mu_{x}^{*} - C \right) \right\} \\ &- 2\alpha_{2} \eta \mu_{x} \alpha A \delta_{1} \left(\mu_{x}^{*} - C \right) + 2\alpha_{1} \alpha_{2} \eta \mu_{x} \left(\mu_{y} \delta_{01} - 2A\alpha C \delta_{1} \right) \end{split} \tag{22}$$

Proof:

$$\begin{split} MSE(t_{p}) &= E(t_{p} - \mu_{y})^{2} \\ &= E\Big[\alpha_{1}\Big\{C - A\alpha Ce_{1} + e_{0}\mu_{y} + BCe_{1}^{2} - \alpha A\mu_{y}e_{0}e_{1}\Big\} + \alpha_{2}\eta\mu_{x}\Big\{e_{1} - A\alpha e_{1}^{2}\Big\} \\ &- C + \alpha Ae_{1}\mu_{y}^{*} - B\mu_{y}^{*}e_{1}^{2}\Big]^{2} \end{split}$$

Squaring and then taking expectations of both sides, we get the MSE of the suggested estimator up to the first order of approximation as

$$\begin{split} MSE(t_{p}) &= \alpha_{1}^{2} \left\{ C^{2} + \mu_{y}^{2} \delta_{0} + \delta_{1} \left(\alpha^{2} A^{2} C^{2} + 2 B C^{2} \right) - 4 \alpha A C \mu_{y} \delta_{01} \right\} + \alpha_{2}^{2} \eta^{2} \mu_{x}^{2} \delta_{1} \\ &+ \left\{ C^{2} + \delta_{1} \left(\alpha^{2} A^{2} \mu_{x}^{2} - 2 B C \mu_{x}^{*} \right) \right\} - 2 \alpha_{1} \left\{ C^{2} + \delta_{1} \left(B C^{2} - B C \mu_{x}^{*} - \alpha^{2} A^{2} C \mu_{x}^{*} \right) + \delta_{01} \alpha A \mu_{y} \left(\mu_{x}^{*} - C \right) \right\} \\ &- 2 \alpha_{2} \eta \mu_{x} \alpha A \delta_{1} \left(\mu_{x}^{*} - C \right) + 2 \alpha_{1} \alpha_{2} \eta \mu_{x} \left(\mu_{y} \delta_{01} - 2 A \alpha C \delta_{1} \right) \end{split}$$

Equation (22) can be written as:

$$MSE(t_{p}) = \alpha_{1}^{2} \phi_{1} + \alpha_{2}^{2} \phi_{2} - 2\alpha_{1} \phi_{3} - 2\alpha_{2} \phi_{4} + 2\alpha_{1} \alpha_{2} \phi_{5} + \phi$$
(23)

Differentiating (23) with respect to (α_1, α_2) and equating them to zero, we get the optimum values of (α_1, α_2) as

$$\alpha_{_{1(opt)}} = \frac{\phi_2 \phi_3 - \phi_4 \phi_5}{\phi_1 \phi_2 - \phi_5^2} \text{ and } \alpha_{_{2(opt)}} = \frac{\phi_1 \phi_4 - \phi_3 \phi_5}{\phi_1 \phi_2 - \phi_5^2}$$

where,
$$\phi_1=C^2+\mu_y^2\delta_0+\delta_1\Big(\alpha^2A^2C^2+2BC^2\Big)-4\alpha AC\mu_y\delta_{01}$$

$$\phi_2=\eta^2\mu_x^2\delta_1$$

$$\begin{split} \phi_3 &= C^2 + \delta_1 \Big(BC^2 - BC\mu_x^* - \alpha^2 A^2 C\mu_x^*\Big) + \delta_{01} \alpha A \mu_y \Big(\mu_x^* - C\Big) \\ \phi_4 &= \eta \mu_x \alpha A \delta_1 \Big(\mu_x^* - C\Big) \\ \phi_5 &= \eta \mu_x \Big(\mu_y \delta_{01} - 2A\alpha C \delta_1\Big) \\ \phi &= C^2 + \delta_1 \Big(\alpha^2 A^2 \mu_x^2 - 2BC\mu_x^*\Big) \end{split}$$

In the Table 2 some estimators are listed which are particular members of the suggested class of estimators t_p for different values of (α, η, λ) .

Table 2: Particular members of the suggested class of estimators t_p

Estimators

	Values of constants		
	α	η	λ
$\mathbf{t}_{1} = \left[\alpha_{1}\overline{\mathbf{y}} + \alpha_{2}\overline{\mathbf{x}} + (1 - \alpha_{1} - \alpha_{2})\mu_{x}\right] \left[\frac{\mu_{x}}{\overline{\mathbf{x}}}\right]$	-1	1	0
$t_2 = \left[\alpha_1 \overline{y} + \alpha_2 (\overline{x} + 1) + (1 - \alpha_1 - \alpha_2)(\mu_x + 1)\right] \left[\frac{\mu_x + 1}{\overline{x} + 1}\right]$	1	1	1
$t_{3} = \left[\alpha_{1}\overline{y} + \alpha_{2}(\overline{x} + 1) + (1 - \alpha_{1} - \alpha_{2})(\mu_{x} + 1)\right] \left[\frac{\mu_{x}}{\overline{x}}\right]^{-1}$	-1	1	1
$t_4 = \left[\alpha_1 \overline{y} + \alpha_2 (\overline{x} + \rho) + (1 - \alpha_1 - \alpha_2)(\mu_x + \rho)\right] \left[\frac{\mu_x + \rho}{\overline{x} + \rho}\right]^{-1}$	-1	1	ρ
$t_{5} = \left[\alpha_{1}\overline{y} + \alpha_{2}(\overline{x} + C_{x}) + (1 - \alpha_{1} - \alpha_{2})(\mu_{x} + C_{x})\right] \left[\frac{\mu_{x} + C_{x}}{\overline{x} + C_{x}}\right]^{-1}$	-1	1	C_x

$$\mathbf{t}_{6} = \left[\alpha_{1}\overline{\mathbf{y}} + \alpha_{2}(\overline{\mathbf{x}} - \mathbf{C}_{x}) + (1 - \alpha_{1} - \alpha_{2})(\mu_{x} - \mathbf{C}_{x})\right] \left|\frac{\mu_{x} - \mathbf{C}_{x}}{\overline{\mathbf{x}} - \mathbf{C}_{x}}\right| \qquad -1 \qquad 1 \qquad -\mathbf{C}_{x}$$

$$\mathbf{t}_{7} = \left[\alpha_{1}\overline{\mathbf{y}} - \alpha_{2}(\overline{\mathbf{x}} + 1) - (1 - \alpha_{1} - \alpha_{2})(\mu_{x} + C_{x})\right] \left[\frac{\mu_{x} + C_{x}}{\overline{\mathbf{x}} + C_{x}}\right]^{-1} - 1 - 1$$

4. EMPIRICAL STUDY

Data statistics: The data used for empirical study has been taken from Gujarati (2007)

Where, Y_i=True consumption expenditure,

X_i=True income,

 μ_y y_i =Measured consumption expenditure,

 $x_i =$ Measured income.

n		μ_{x}	σ_{y}^{2}	σ_{x}^{2}	ρ	$\sigma_{\rm u}^2$	$\sigma_{\rm v}^2$
10	127	170	1278	3300	0.964	36	36

The percentage relative efficiencies (PRE) of various estimators with respect to the mean per unit estimator of \overline{Y} , that is \overline{y} , can be obtained as

$$PRE(.) = \frac{Var(\overline{y})}{MSE(.)} *100$$

Table 3: MSE and PRE of estimators with respect to \bar{y}

Estimators	Mean Square Error	Percent Relative Efficiency
\overline{y}	131.4	100
\overline{y}_{R}	21.7906	603.0118
\overline{y}_d	13.916	944.1285

\overline{y}_{s}	13.916	944.1285
\overline{y}_{DS}	13.916	944.1285
$\mathbf{t}_{_{1}}$	10.0625	1236.648
t_2	9.92677	1323.693
t_3	6.82471	1925.356
t_4	6.9604	1887.818
t ₅	9.3338	1407. 774
t_6	11.9246	1101.923
t ₇	7.9917	1644.194

5. PERFORMANCE OF SUGGESTED ESTIMATOR IN STRATIFIED RANDOM SAMPLING

SYMBOLS AND SETUP

Consider a finite population $U=(u_1,u_2,...,u_N)$ of size N and let X and Y respectively be the auxiliary and study variables associated with each unit $u_j=(j=1,2,....,N)$ of population. Let the population of N be stratified in to L strata with the h^{th} stratum containing N_h units, where h=1,2,3,...,L such that $\sum_{i=1}^L N_h = N$. A simple random size n^h is drown without replacement from the h^{th} stratum such that $\sum_{i=1}^L n_h = n$. Let (y_{hi}, X_{hi}) of two characteristics (Y,X) on i^{th} unit of the h^{th} stratum, where $i=1,2,...,N_h$. In addition let

$$(\overline{y}_h = \frac{1}{n_h} \sum_{i=1}^{n_h} y_{hi}, \overline{x}_h = \frac{1}{n_h} \sum_{i=1}^{n_h} x_{hi}),$$

$$(\bar{y}_{st} = \sum_{i=1}^{n_h} W_h \bar{y}_h, \bar{x}_{st} = \sum_{i=1}^{n_h} W_h \bar{x}_h),$$

$$(\,\mu_{Yh} = \frac{1}{N_h} \sum_{i=1}^{N_h} y_{hi}^{}, \mu_{Xh}^{} = \frac{1}{N_h} \sum_{i=1}^{N_h} x_{hi}^{}\,),$$

And ($\mu_Y = \sum_{h=1}^L W_h \mu_{Yh}$, $\mu_X = \sum_{i=1}^{N_h} W_h \mu_{Xh}$) be the samples means and population means of (Y,X)

respectively, where $W_h = \frac{N_h}{N}$ is the stratum weight. Let the observational or measurement errors be

$$\mathbf{u}_{\mathrm{hi}} = \mathbf{y}_{\mathrm{hi}} - \mathbf{Y}_{\mathrm{hi}} \tag{24}$$

$$\mathbf{v}_{hi} = \mathbf{X}_{hi} - \mathbf{X}_{hi} \tag{25}$$

Where u_{hi} and v_{hi} are stochastic in nature and are uncorrelated with mean zero and variances σ_{Vh}^{2} and σ_{Uh}^{2} respectively. Further let ρ_{h} be the population correlation coefficient between Y and X in the h^{th} stratum. It is also assumed that the finite population correction terms $(1-f_{h})$ and (1-f) can be ignored where $f_{h} = \frac{n_{h}}{N_{h}}$ and $f = \frac{n}{N}$.

LARGE SAMPLE APPROXIMATION

Let,

$$\bar{y}_{st} = \mu_{y}(1 + e_{0h})$$
, and $\bar{x}_{st} = \mu_{x}(1 + e_{1h})$

such that, $E(e_{0h}) = E(e_{1h}) = 0$,

$$E(e_{0h}^2) = \frac{C_{Yh}^2}{n_h} \left(1 + \frac{\sigma_{Uh}^2}{\sigma_{Yh}^2} \right) = \frac{C_{Yh}^2}{n_h \theta_{Yh}} = \nabla_0,$$

$$E(e_{1h}^{2}) = \frac{C_{Xh}^{2}}{n_{h}} \left(1 + \frac{\sigma_{Vh}^{2}}{\sigma_{Xh}^{2}} \right) = \frac{C_{Xh}^{2}}{n_{h}\theta_{Xh}} = \nabla_{1},$$

$$E(e_{0h}e_{1h}) = \frac{1}{n_h} \rho_h C_{Yh} C_{Xh} = \nabla_{01}.$$

$$\text{where, } C_{Yh} = \frac{\sigma_{Yh}}{\mu_{Yh}}, \, C_{Xh} = \frac{\sigma_{Xh}}{\mu_{Xh}}, \, \theta_{Yh} = \frac{\sigma_{Uh}^2}{\sigma_{Uh}^2 + \sigma_{Yh}^2} \, \text{and} \, \, \theta_{Xh} = \frac{\sigma_{Vh}^2}{\sigma_{Vh}^2 + \sigma_{Xh}^2}.$$

EXISTING ESTIMATORS AND THEIR PROPERTIES

 \overline{y}_{st} is usual unbiased estimator in stratified random sampling scheme.

The usual combined ratio estimator in stratified random sampling in the presence of measurement error is defined as-

$$T_{R} = \overline{y}_{st} \frac{\mu_{x}}{\overline{x}_{st}}$$
 (26)

The usual combined product estimator in the presence of measurement error is defined as-

$$T_{PR} = \overline{y}_{st} \frac{\overline{x}_{st}}{\mu_{x}}$$
 (27)

Combined difference estimator in stratified random sampling is defined in the presence of measurement errors for a population mean, as

$$T_{D} = \overline{y}_{st} + d(\mu_{x} - \overline{x}_{st})$$
 (28)

The variance and mean square term of above estimators, up to the first order of approximation, are respectively given by

$$Var(\overline{y}_{st}) = \frac{C_{Xh}^2}{n_h} \left(1 + \frac{\sigma_{Uh}^2}{\sigma_{Yh}^2} \right)$$
 (29)

$$MSE(T_R) = \sum_{h=1}^{L} \frac{W_h^2}{n_h} \left| \frac{\sigma_{Yh}^2}{\theta_{Yh}} + R \left(\frac{\sigma_{Xh}^2}{\theta_{Xh}} \right) \right| \left(R - 2\beta_{YXh} \theta_{Xh} \right)$$
(30)

$$MSE(T_{P}) = \sum_{h=1}^{L} \frac{W_{h}^{2}}{n_{h}} \left[\frac{\sigma_{Yh}^{2}}{\theta_{Yh}} + R \left(\frac{\sigma_{Xh}^{2}}{\theta_{Xh}} \right) \right] \left(R + 2\beta_{YXh} \theta_{Xh} \right)$$
(31)

$$MSE(T_{D}) = \sum_{h=1}^{L} \frac{W_{h}^{2}}{n_{h}} \left(\frac{\sigma_{Yh}^{2}}{\theta_{Yh}}\right) + d^{2} \sum_{h=1}^{L} \frac{W_{h}^{2}}{n_{h}} \left(\frac{\sigma_{Xh}^{2}}{\theta_{Xh}}\right) - 2d \sum_{h=1}^{L} \frac{W_{h}^{2}}{n_{h}} \beta_{XYh} \sigma_{Xh}^{2}$$
(32)

where,
$$d_{opt} = \frac{\displaystyle\sum_{h=1}^{L} \frac{W_h^2}{n_h} \beta_{XYh} \sigma_{Xh}^2}{\displaystyle\sum_{h=1}^{L} \frac{W_h^2}{n_h} \left(\frac{\sigma_{Xh}^2}{\theta_{Xh}}\right)}$$

6. SUUGESTED ESTIMATOR AND ITS PROPERTIES

Let B(.) and M(.) denote the bias and mean square error (M.S.E) of an estimator under given sampling design. Estimator t_p defined in equation (19) can be written in stratified random sampling as

$$T_{P} = \left[\beta_{1} \overline{y}_{st} + \beta_{2} \overline{x}_{st}^{*} + (1 - \beta_{1} - \beta_{2}) \mu_{x}^{*}\right] \left[\frac{\mu_{x}^{*}}{\overline{x}_{st}^{*}}\right]^{\beta}$$
(33)

where (α_1,α_2) are suitably chosen scalars such that MSE of proposed estimator is minimum, $\overline{x}_{st}^* (= \eta \overline{x}_{st} + \lambda)$, $\mu_x^* (= \eta \mu_x + \lambda)$ with (n,λ) are either constants or functions of some known population parameters. Here it is interesting to note that some existing estimators have been found particular members of proposed class of estimators T_p for different values of $(\alpha_1,\alpha_2,\alpha,\eta,\lambda)$, which are summarized in Table 4.

Table 4: Members of proposed class of estimators T_p

Estimators	Values of Constants					
	$\alpha_{_1}$	α_2	α	η	λ	
\overline{y}_{st} [Usual unbiased]	1	0	0	-	-	
T_R [Usual ratio]	1	0	1	1	0	
T_{PR} [Usual product]	1	0	-1	1	0	
T_D [Usual difference]	1	α_{2}	0	-1	μ_{x}	

Theorem 2.1: Estimator T_p in terms of e_i ; i = 0,1 by ignoring the terms $E(e_{ih}^r e_{jh}^s)$ for (r+s)>2, where r,s=0,1,2... and i=0,1; j=1, can be written as

$$\begin{split} T_{P} = & \left[\mu_{x}^{*} - \beta A' e_{1h} \mu_{x}^{*} + B' \mu_{x}^{*} e_{1h}^{2} + \beta_{1} \left\{ C' - \beta A' C e_{1h} + B' C' e_{1h}^{2} + e_{0h} \mu_{y} - \beta A' \mu_{y} e_{0h} e_{1h} \right\} \\ & + \beta_{2} \eta \mu_{x} \left\{ e_{1h} - \beta A' e_{1h}^{2} \right\} \right] \end{split}$$

where,
$$A' = \frac{\eta \mu_x}{\eta \mu_x + \lambda}$$
, $B' = \frac{\beta(\beta + 1)}{2} A'^2$ and $C' = \mu_y - \mu_x^*$.

Proof

$$T_{P} = \left[\beta_{1}\overline{y}_{st} + \beta_{2}\overline{x}_{st}^{*} + (1 - \beta_{1} - \beta_{2})\mu_{x}^{*} \left[\frac{\mu_{x}^{*}}{\overline{x}_{st}^{*}}\right]^{\beta}\right]$$

$$= \left[\beta_{1}(1 + e_{0h}) + \beta_{2}\eta \mu_{x}e_{1h} + (1 - \beta_{1})\mu_{x}^{*}\right][1 + A'e_{1h}]^{-\beta}$$
(34)

We assume $|A'e_{1h}| < 1$, so that the term $(1 + A'e_{1h})^{-\beta}$ is expandable. Thus by expanding the right hand side (20) and neglecting the terms of e's having power greater than two, we have

$$\begin{split} T_p = & \left[\mu_x^* - \beta A' e_{1h} \mu_x^* + B' \mu_x^* e_{1h}^2 + \beta_1 \left\{ \! C' \! - \! \beta A' C' e_{1h} + B' C' e_{1h}^2 + e_{0h} \mu_y - \beta A' \mu_y e_{0h} e_{1h} \right. \right\} \\ & + \beta_2 \eta \mu_x \left\{ \! e_{1h} - \! \beta A' e_{1h}^2 \right\} \end{split}$$

Theorem: 2.2 Bias of T_p is given by

$$B(T_{P}) = \left[B' \mu_{x}^{*} \nabla_{1} + \beta_{1} \left\{ B' C' \nabla_{1} - \beta A' \mu_{y} \nabla_{01} \right\} - \beta_{2} \eta \mu_{x} A' \beta \nabla_{1} \right]$$
(35)

Proof:

$$B(T_{P}) = E(T_{P} - \mu_{v})$$

$$\begin{split} =& E\left[\mu_{x}^{*}-\mu_{y}-\beta A'e_{1h}\mu_{x}^{*}+B'\mu_{x}^{*}e_{1h}^{2}+\beta_{1}\left\{\!C'\!-\!\beta A'C'e_{1h}+B'C'e_{1h}^{2}+e_{0h}\mu_{y}-\beta A'\mu_{y}e_{0h}e_{1h}\right.\right\}\\ &\left.+\beta_{2}\eta\mu_{x}\left\{\!e_{1h}-\beta A'e_{1h}^{2}\right\}\!\right] \end{split}$$

$$= \left[\mathbf{B}' \boldsymbol{\mu}_{x}^{*} \nabla_{1} + \beta_{1} \left\{ \mathbf{B}' \mathbf{C}' \nabla_{1} - \beta \mathbf{A}' \boldsymbol{\mu}_{y} \nabla_{01} \right\} - \beta_{2} \beta \eta \boldsymbol{\mu}_{x} \mathbf{A}' \nabla_{1} \right]$$

where, ∇_{0} , ∇_{1} and ∇_{01} are already defined in section 3.

Theorem: 2.3 Mean square error of T_p, up to the first order of approximation is given by

$$\begin{split} MSE(T_{P}) &= \beta_{1}^{2} \left\{ C^{'2} + \mu_{y}^{2} \nabla_{0} + \nabla_{1} \left(\beta^{2} A^{'2} C^{'2} + 2 B^{'} C^{'2} \right) - 4 \beta A^{'} C^{'} \mu_{y} \nabla_{01} \right\} + \beta_{2}^{2} \eta^{2} \mu_{x}^{2} \nabla_{1} \\ &+ \left\{ C^{'2} + \nabla_{1} \left(\beta^{2} A^{'2} \mu_{x}^{2} - 2 B^{'} C^{'} \mu_{x}^{*} \right) \right\} - 2 \beta_{1} \left\{ C^{'2} + \nabla_{1} \left(B^{'} C^{'2} - B^{'} C^{'} \mu_{x}^{*} - \beta^{2} A^{'2} C^{'} \mu_{x}^{*} \right) + \nabla_{01} \beta A \mu_{y} \left(\mu_{x}^{*} - C^{'} \right) \right\} \\ &- 2 \beta_{2} \eta \mu_{x} \beta A \nabla_{1} \left(\mu_{x}^{*} - C^{'} \right) + 2 \beta_{1} \beta_{2} \eta \mu_{x} \left(\mu_{y} \nabla_{01} - 2 A^{'} \beta C^{'} \nabla_{1} \right) \end{split} \tag{36}$$

Proof:

$$MSE(T_{P}) = E(T_{P} - \mu_{V})^{2}$$

MSE(T_p) can also be written as

$$MSE(T_{P}) = \beta_{1}^{2} \chi_{1} + \beta_{2}^{2} \chi_{2} - 2\beta_{1} \chi_{3} - 2\beta_{2} \chi_{4} + 2\beta_{1} \beta_{2} \chi_{5} + \chi$$
(37)

Differentiating equation (37) with respect to (β_1, β_2) and equating it to zero, we get the optimum values of (β_1, β_2) respectively, as

$$\begin{split} \beta_{1(\text{opt})} &= \frac{\chi_2 \chi_3 - \chi_4 \chi_5}{\chi_1 \chi_2 - \chi_5^2} \text{ and } \beta_{2(\text{opt})} = \frac{\chi_1 \chi_4 - \chi_3 \chi_5}{\chi_1 \chi_2 - \chi_5^2} \\ \text{where, } & \chi_1 = C'^2 + \mu_y^2 \nabla_0 + \nabla_1 \Big(\beta^2 A'^2 \ C'^2 + 2 B' C'^2 \Big) - 4 \beta A' C' \mu_y \nabla_{01} \\ & \chi_2 = \eta^2 \mu_x^2 \nabla_1 \\ & \chi_3 = C'^2 + \nabla_1 \Big(B C^2 - B' C' \mu_x^* - \beta^2 A'^2 \ C' \mu_x^* \Big) + \nabla_{01} \beta A' \mu_y \Big(\mu_x^* - C' \Big) \\ & \chi_4 = \eta \mu_x \beta A' \nabla_1 \Big(\mu_x^* - C' \Big) \end{split}$$

$$\chi_{5} = \eta \mu_{x} \left(\mu_{y} \nabla_{01} - 2A' \beta C' \nabla_{1} \right)$$

$$\chi = C'^{2} + \nabla_{1} \left(\beta^{2} A'^{2} \mu_{x}^{2} - 2B' C' \mu_{x}^{*} \right)$$

With the help of these values, we get the minimum MSE of the suggested estimator T_p.

7. DISCUSSION AND CONCLUSION

In the present study, we have proposed difference-type class of estimators of the population mean of a study variable when information on an auxiliary variable is known in advance. The asymptotic bias and mean square error formulae of suggested class of estimators have been obtained. The asymptotic optimum estimator in the suggested class has been identified with its properties. We have also studied some traditional methods of estimation of population mean in the presence of measurement error such as usual unbiased, ratio, usual difference estimators suggested by Srivastava(1967), dubey and singh(2001), which are found to be particular members of suggested class of estimators. In addition, some new members of suggested class of estimators have also been generated in simple random sampling case. An empirical study is carried to throw light on the performance of suggested estimators over other existing estimators using simple random sampling scheme. From the Table 3, we observe that suggested estimator 13 performs better than the other estimators considered in the present study and which reflects the usefulness of suggested method in practice.

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